

Increasing Confidence in Machine Learned (ML) Functional Behavior during Artificial Intelligence (AI) Development using Training Data Set Measurements

Presented for the Acquisition Research Symposium 2021
Special Webinar on Developing AI in Defense Programs, March 3, 2021

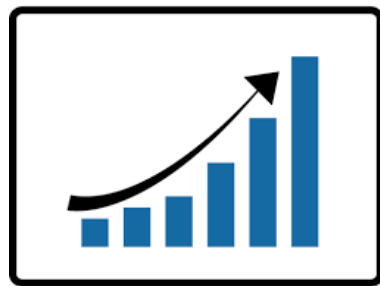
Presented by Bruce Nagy



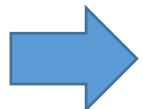
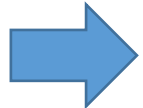
Motivation: Naval Ordnance Safety and Security Activity (NOSSA) Concerned about the “Garbage In, Garbage Out” Phenomena



Quality of the Training Set
(Composition)

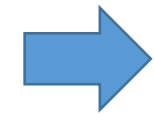


Quantity of the Training Set
(Size)



0.633666667	0.200333333	0.483666667	0.000333333	0.000333333
0.650333333	0.000333333	0.733666667	0.000333333	0.000333333
0.667	0.350333333	0.700333333	0.000333333	0.000333333
0.467	0.233666667	0.550333333	0.217	0.333666667
0.767	0.000333333	0.417	0.000333333	0.000333333
0.000333333	0.300333333	0.667	0.433666667	0.383666667
0.467	0.583666667	0.000333333	0.000333333	0.000333333
0.000333333	0.233666667	0.000333333	0.750333333	0.367
0.283666667	0.700333333	0.383666667	0.783666667	0.333666667
0.267	0.667	0.000333333	0.700333333	0.833666667
0.183666667	0.450333333	0.250333333	0.483666667	0.533666667
0.000333333	0.633666667	0.000333333	0.000333333	0.000333333
0.000333333	0.267	0.000333333	0.733666667	0.000333333
0.250333333	0.767	0.267	0.783666667	0.750333333
0.000333333	0.000333333	0.183666667	0.000333333	0.733666667
0.000333333	0.267	0.117	0.350333333	0.700333333
0.000333333	0.000333333	0.000333333	0.300333333	0.717

Results of Using Training Set
To Develop AI/ML Algorithm
(Array of Weights)



Operational Environment



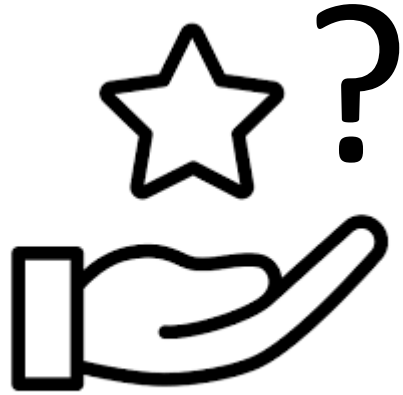
Deployed Algorithm



Confidence in Functional Performance

?

Synthetic vs Real Data – the Training Conundrum



Uncertainty in Synthetic Accuracy



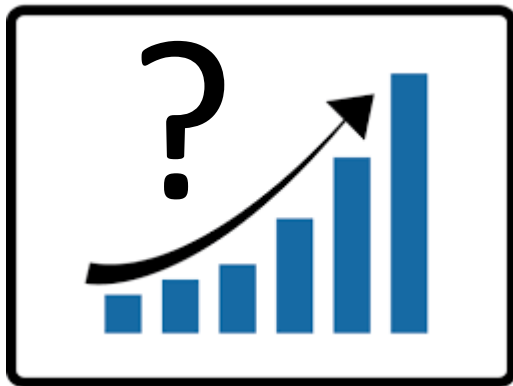
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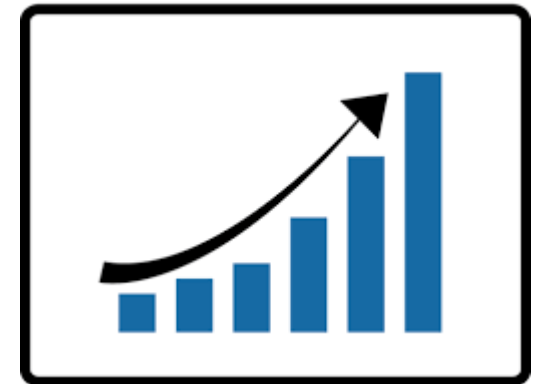
Synthetic

vs

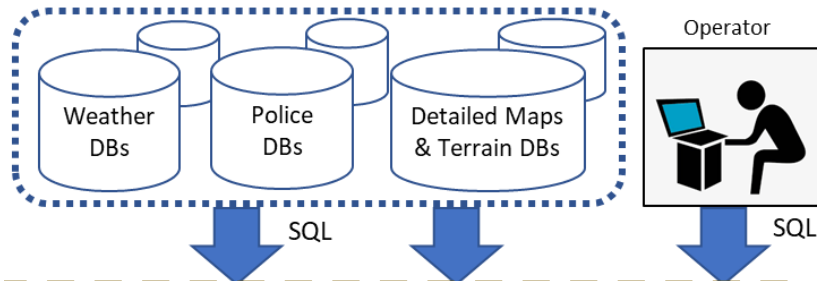
Real



Does it adequately replicate noise?
Does it adequately replicate reality?



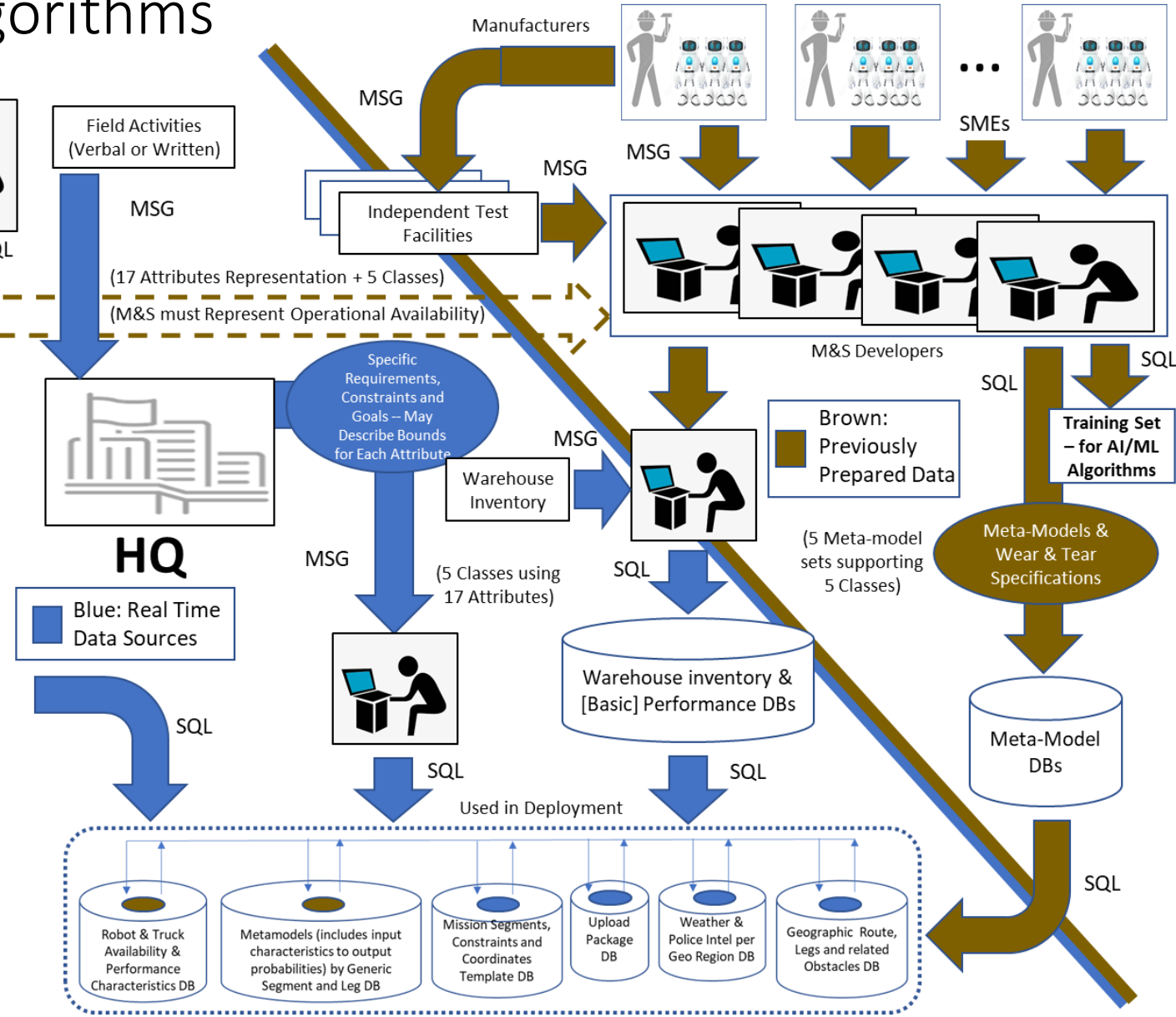
Data Sources Used by ML Algorithms



Inputs & Attributes	Used to Understand Environment	Used to Understand Route	Used by Meta-Model (Variables to Affect Robot and Route Selection)
Experience [Operator]	Weather & Police Intel per Geo Region DB	Geographic Route, Legs and related Obstacles DB	User Expectations Input (Basically Predicting the Future)
Accountability [Operator]			Low, Sufficient, High [Expectation - Affect on Time]
Loader [Mechanism]			Low, Sufficient, High [Expectation - Affect on Time]
Weight [Robots]			Poor, Fair, Good [Expectation - Affect on Time]
Secure [Robots]			Outside Tolerance, Within Tolerance [Expectation - Affect on Time]
Damage [Robots]			Loosely, Tightly, Firm [Expectation - Affect on Time]
Distance > 5 miles (distanceT)		X miles [Affect on Time]	None, Minor, Significant [Expectation - Affect on Time]
Distance <= 5 miles (distanceR)		Y miles [Affect on Time]	
Surface		Loose, Slippery, Firm [Affect on Time]	
Weather	Raining Hard, Raining Slightly, Sunny [Affect on Time]		
Incline		Steep Up, Flat [Affect on Time]	
Speed > 5 mph (propulationT)			Slow, Medium, Fast [Expectation - Affect on Time]
Speed <= 5 mph (propulationR)			Slow, Medium, Fast [Expectation - Affect on Time]
Stress [Robots]			Severe, Minor, None [Expectation - Affect on Time]
Identification [Recipient]			Unsure, Likely, Confident [Expectation - Affect on Time]
Access [to Recipient]		Highly Obstructed, Obstructed, Clear [Affect on Time]	
Mechanics [of Robot Arms]			Limited, Glitchy, Working [Expectation - Affect on Time]

Will any of this data be sparse or missing?

Operator guesses in real time about the future of these 3 Attributes



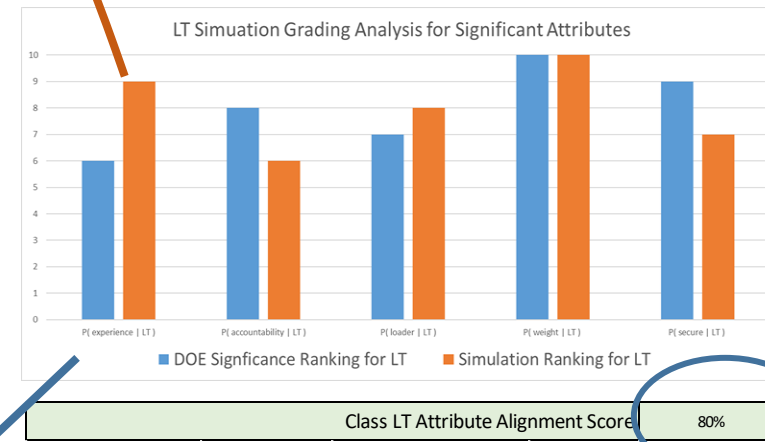
Specific Requirements, Constraints and Goals – May Describe Bounds for Each Attribute

Experience [Operator]	Low, Sufficient, High [Expectation - Affect on Time]
Accountability [Operator]	Low, Sufficient, High [Expectation - Affect on Time]
Loader [Mechanism]	Poor, Fair, Good [Expectation - Affect on Time]
Weight [Robots]	Outside Tolerance, Within Tolerance [Expectation - Affect on Time]
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How does TSAT assess Quality?

DOE Significance Ranking for LT	Simulation Ranking for LT	P(LT) = 0.097087379	Weighted Number
6	9	P(experience LT) = 0.702	1.35
8	6	P(accountability LT) = 0.602	1.20
7	8	P(loader LT) = 0.602	1.40
10	10	P(weight LT) = 0.702	2.50
9	7	P(secure LT) = 0.602	1.58
1		P(damage LT) = 0.002	
3		P(distanceT LT) = 0.202	
1		P(distanceR LT) = 0.002	
2		P(surface LT) = 0.402	
5		P(weather LT) = 0.302	
4		P(incline LT) = 0.302	
1		P(propulationT LT) = 0.002	
1		P(propulationR LT) = 0.002	
6		P(stress LT) = 0.402	
1		P(identification LT) = 0.002	
1		P(access LT) = 0.002	
1		P(mechanics LT) = 0.002	

This percentage describes how well what was required matches what was simulated. In this case it was 80%.



From the simulation results that created the training data, was what you expected in terms of precedence of data source available for an attribute represented in the simulation?

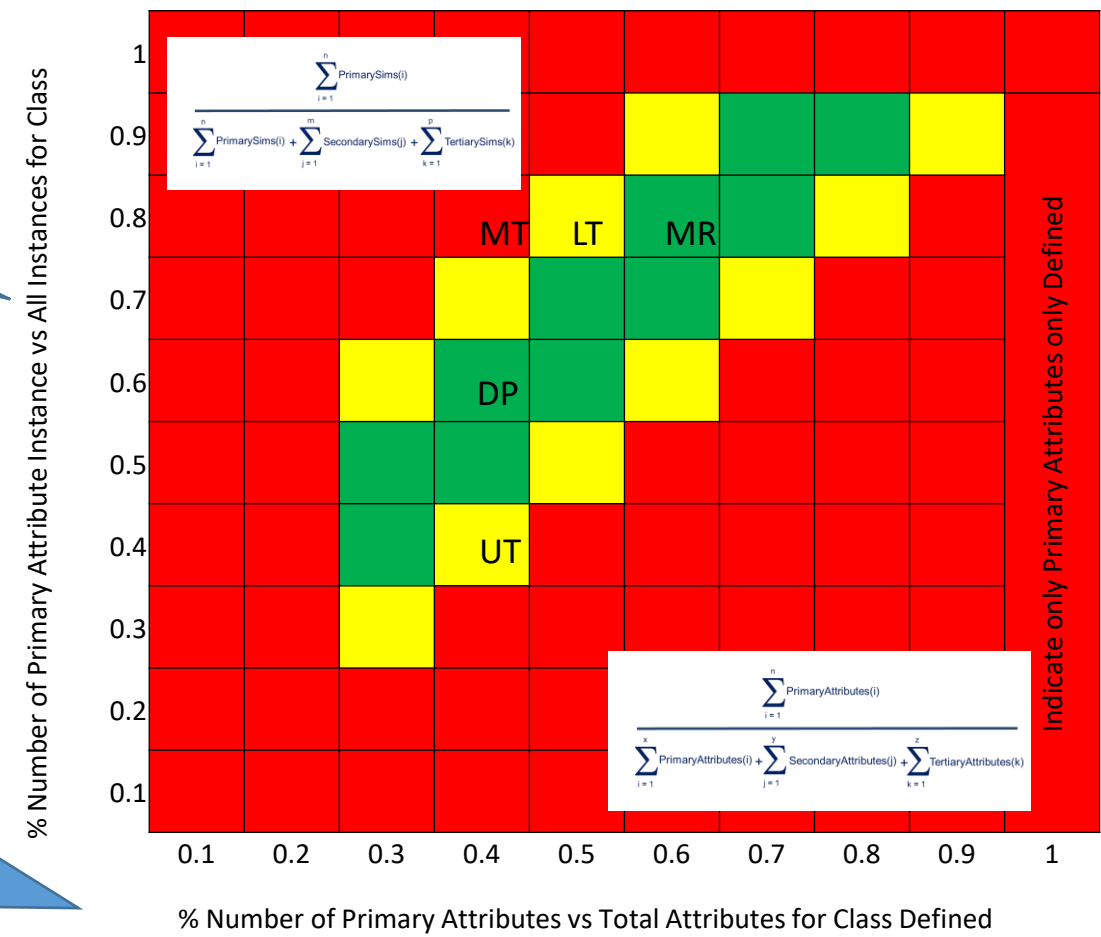
Source to Attribute Ratios for 2nd (StAR-n) Order Grouping Matrix

(Defined based on Deployed Operational Conditions transcribed into Requirements)

Instances from simulations or collected live data that created quantity of training data containing primary attributes

This matrix supports primary and secondary analysis only – used as an example

This matrix chart is for analyzing quantity regarding primary attributes to others



DOE Focus on Creating Sufficient Training Data by asking the question: How much on the Training Data should consist of Primary vs Secondary Attributes depends on Data Sources

■ Evidence of Simulations
 ■ + Justification to Handle Unexpected
 ■ + External Source to Monitor & Intercede

Note: Matrices can be created for Primary, Secondary and Tertiary attributes, not just Primary!



At Requirements stage and checked during Architecture review:

- **First Step:** Create a ten by ten matrix, labeling each axis from zero to 1.
- **Second Step:** Label the horizontal axis “% Number of Primary Attributes vs Total Attributes for Class” and the vertical axis “% Number of Primary Attribute Instances vs All Instances for Class”
- **Third Step:** Determine a three-color zone scheme (see example), where green indicates that the ratio fell within acceptable limits, yellow indicates ratio is boarder line acceptable, and red color zone indicated ration is outside expected limits. Color of the zone should how well training data reflects operational environment. Based on color zone, determine evidence justification. Examples (used for guidance only) are described below:
 - Zone Green: Evidence of data by showing appropriate n-th order groups of training sets collected or generated by the simulations, including success rates as well as the TSAT results.
 - Zone Yellow: Zone Green evidence plus justification on why n-th group precedence can still handle the unexpected and provide acceptable success rates.
 - Zone Red: Zone Green and Yellow evidence as to how this algorithm is going to be supervised or monitored when operationally unexpected events occur.

When training set is produced during Algorithm code review:

- **Fourth Step:** Calculate the σ and δ (see Figure 6 as an example) ratios. Each ratio should be less than 1. The example below is for primary attributes, but can be done for any n-th order attributes:
 - σ (by Class) = (Number of Primary Attributes / Number of All Attributes) ≤ 1 .
 - δ (by Class) = (Number of all Primary Instances / Number of All Instances) ≤ 1 .
- **Fifth Step:** Plot (x, y) using (σ , δ) pair of numbers and assess where the pair fall within the color zones to determine support action. See example.
 - Zone Green: Evidence of data by showing appropriate n-th order groups of training sets collected or generated by the simulations, including success rates as well as the TSAT results.
 - Zone Yellow: Zone Green evidence plus justification on why n-th group precedence can still handle the unexpected and provide acceptable success rates.
 - Zone Red: Zone Green and Yellow evidence as to how this algorithm is going to be supervised or monitored when operationally unexpected events occur.



Example of for Load Truck (LT)

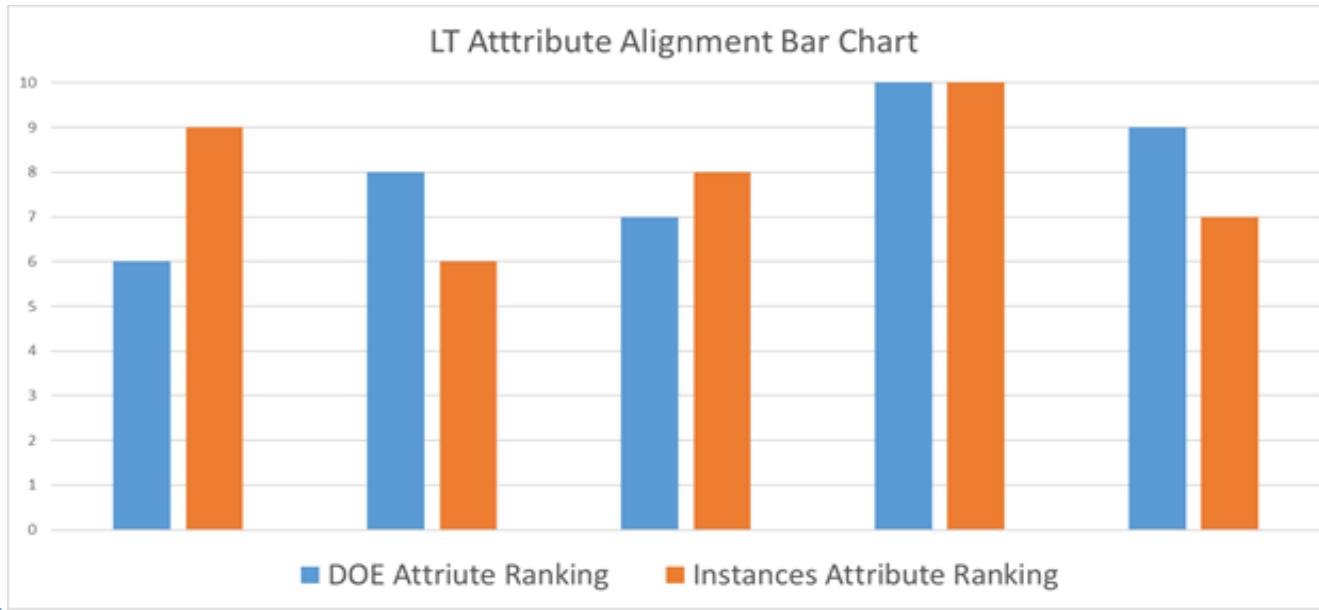
TSAT

StAR-n

Acceptance Threshold Defined in Requirements

What rigor score is acceptable?

These ratios need to be defined in requirements and then compared after training set is generated

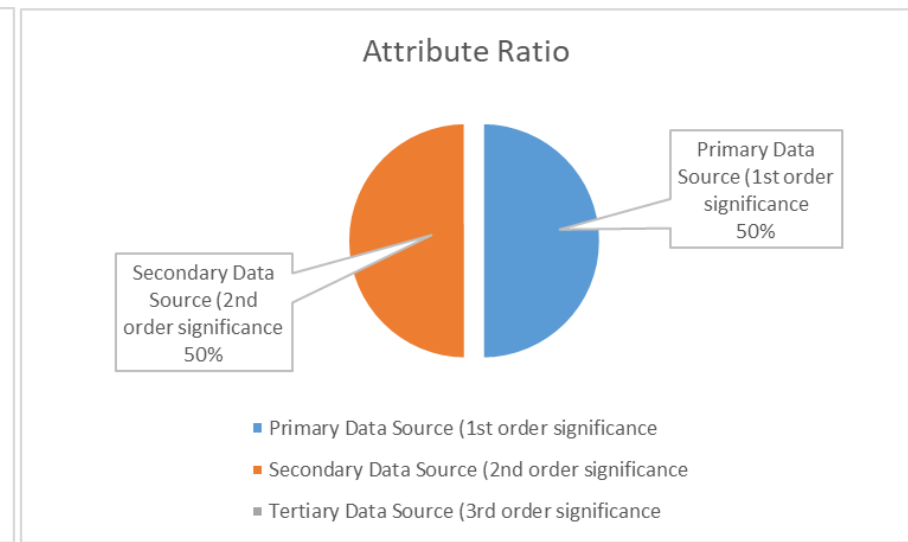
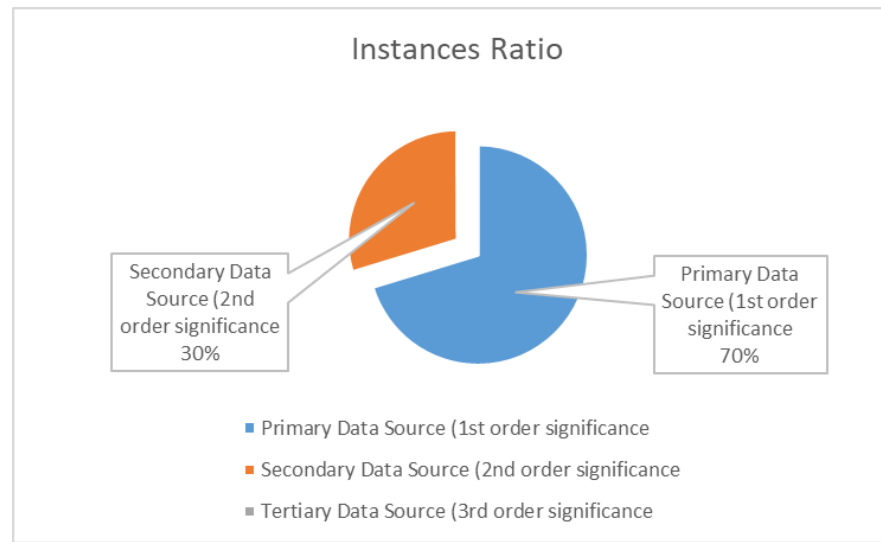


Note: Expected from DOE compared to Actuals from measuring how often the attributes were simulated

Another graph could be used for less significant variables?

Class LT Attribute Alignment Score	80%
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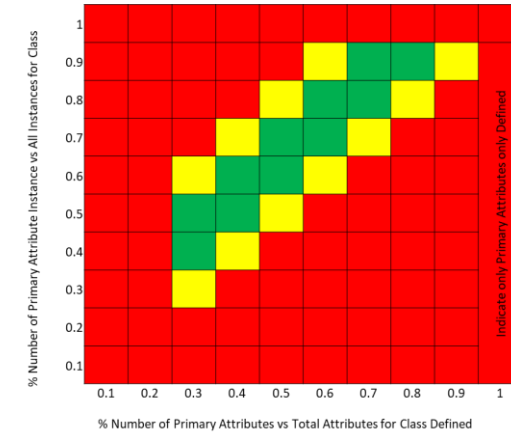
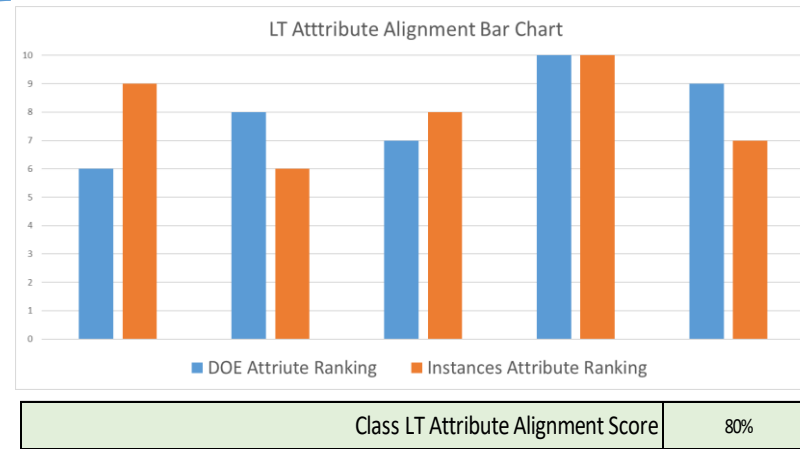
Scale: 100% (highest level of attribute alignment between operations * training set)



TSAT (Quality) and STAR-n (Quantity) Analysis of M&S

These examples would be modified to suite operational deployment conditions and then defined in requirements. Once defined, the requirements would be compared to simulation generated data set.

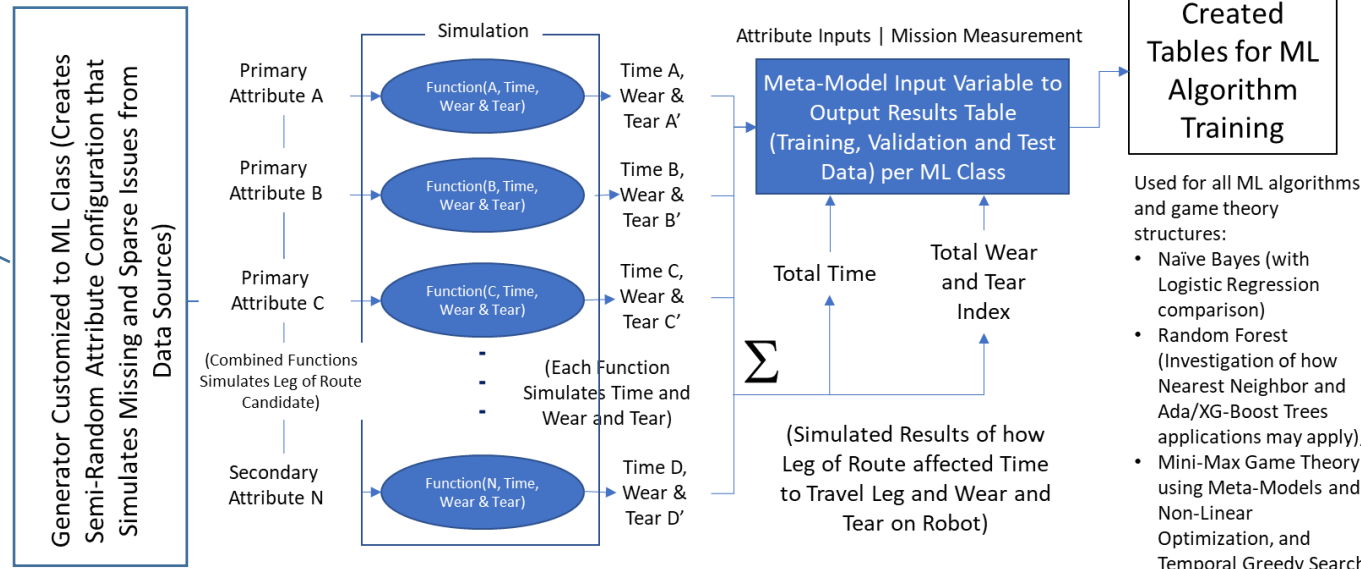
Does it represent the primary, secondary and tertiary data sources adequately?



Does it seem reasonable with regard to ratios associated with the data sources?

Am I producing the right noise output needed to create training data that represents the DOI and Operational Needs?

Both TSAT and STAR-n are used to describe how well the training data was organized using quality and quantity measurements



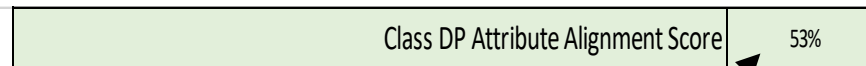
TSAT and StAR-n Concerns (Remember this is about your Training Data)...

TSAT

Example 1 (Poor focus)



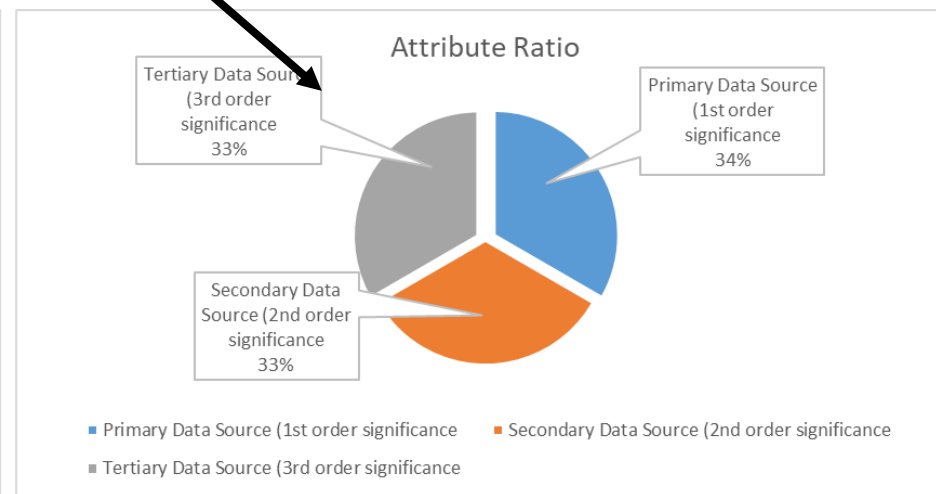
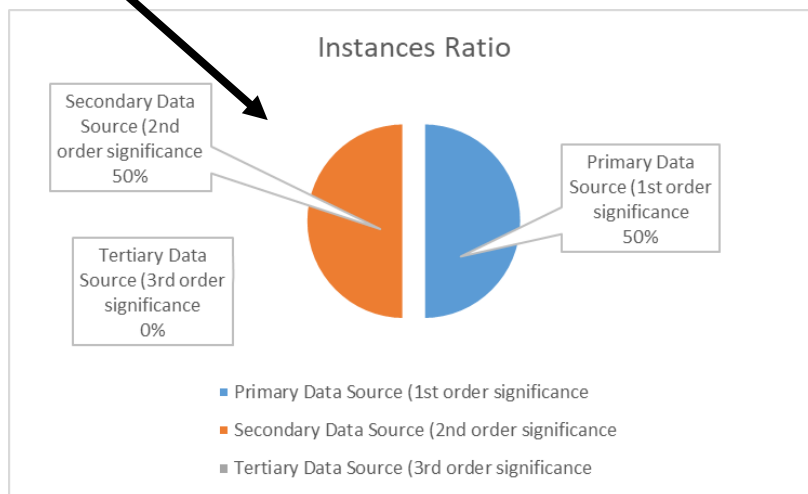
Example 2 (Marginal focus)



Issue: What DOE determined to be significant attributes is NOT what this M&S developer is focusing within his simulation model in generating a data set

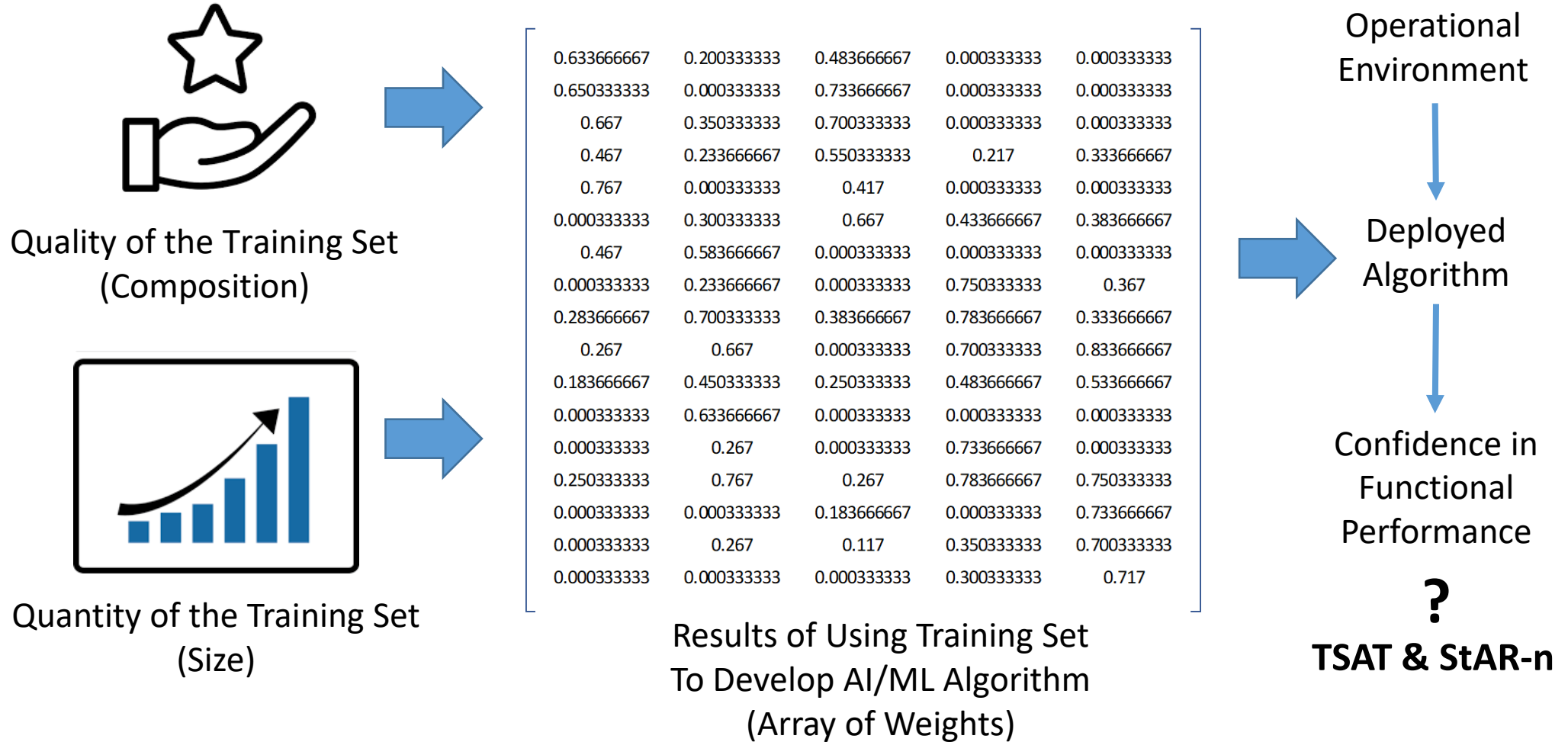
Why are there NO simulations being preformed on 3rd order attributes when there are 3rd order attributes?

StAR-n



As a reminder: The order significance sources relates to primary, secondary and tertiary data sources providing the related attributes in the algorithm. In the above example, it indicates that the operational environment will have 3rd order attributes to support noisy environments, yet the M&S is not modeling that situation. Therefore, given these graphs, the ML algorithm will not be trained properly.

Naval Ordnance Safety and Security Activity (NOSSA) Addressing the “Garbage In, Garbage Out” Concern



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