

SEA-21A

Over the Horizon
Surface-on-Surface Engagement
in the Contested Littorals

Final Progress Review

5 Jun 2015





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The U.S. Navy should invest in unmanned aerial vehicles (UAVs) operated from within a tactical, offensive, independent Surface Action Group to facilitate organic over the horizon (OTH) first strike capabilities in an anti-access/area-denial (A2/AD) environment.

"The surface force is taking the offensive to give the operational commander options to employ naval combat power in any anti-access/area-denial (A2/AD) environment."

VADM Thomas Rowden Commander, Naval Surface Forces



SEA-21A Tasking Statement

OPNAV N9I:

SEA 21A Tasking

Maritime ISR in the Contested Littorals

"Design a fleet system of systems and concept of operations for employment of a cost effective and resilient maritime ISR system capable of collecting, fusing, and disseminating critical environmental and threat information in a contested littoral area in the 2025-2030 timeframe. Consider manned and unmanned systems in all domains to provide sufficient information to support effective tactical offensive operations. Consider employment requirements, operating areas, bandwidth and connectivity, interoperability, sensor data processing, transfer and accessibility, logistics, and basing support in forward areas or from CONUS bases. Generate system requirements for platforms, sensors, and communications in a challenging EM environment. Evaluate swarm concepts for inclusion in your solution. Then develop alternative architectures for platforms, sensors, manning, command and control, intelligence collection/dissemination and consumption, communication and network connectivity, and operational procedures. Address the costs and effectiveness of your alternatives."

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SEA-21A Tasking Statement

Revised:

Over-The-Horizon Surface-on-Surface Engagement in the Contested Littorals

Design a maritime ISR&T system of systems and concept of operations capable of detecting, classifying, and engaging targets in support of organic over-the-horizon tactical offensive operations in a contested littoral area in the 2025-2030 timeframe.

Consider the following:

- Manned and unmanned systems with an IOC by 2020
- Requirements, limitations, operating area, bandwidth and connectivity, EM degradation, interoperability, compatibility, logistics, and forward deployment
- Alternative architectures and their comparative effectiveness and costs



Present Day

U.S. Navy surface combatants currently lack the organic capability to find, fix, track, target, engage, and assess (F2T2EA) another surface vessel over the horizon (OTH) in a contested littoral environment.



YJ-12 ASM 250 NM









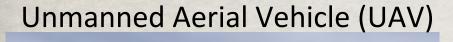


Over the Horizon Targeting: 2025

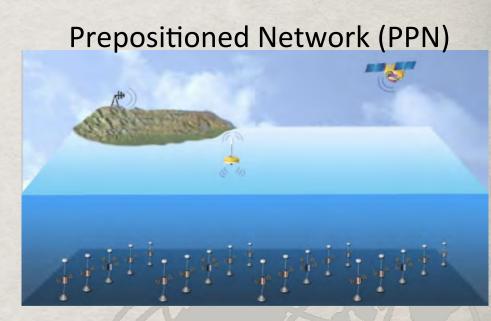
- A2AD: The denied use of an aircraft carrier and its assets
- Littorals: The South China Sea
- Enemy's Target Range: 250 nm
- OTH-capable missile: compatible with all architectures



Selected Architectures







Key Performance Parameters (KPP)

- Performance
 Vulnerability
- Mobility
 Compatibility
- Deployability
 Interoperability
- Adaptability



Unmanned Aerial Vehicle



Purpose

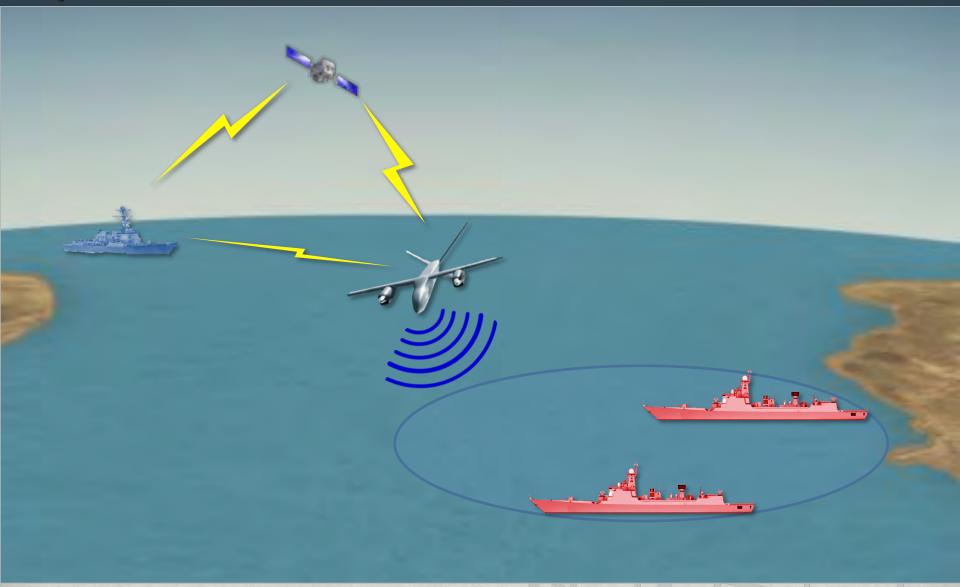
- Organic OTH targeting
- Far-reaching
- Individual CO initiative

Expectations / Limitations

- SAG awareness through multiple lines
- UAV is single point of failure
- 1 UAV 1 platform



Unmanned Aerial Vehicle CONOPS



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Prepositioned Network

Purpose

- Networked information and targeting data on demand
- Consistency for targeting platforms through continuously updated information
- Persistent coverage

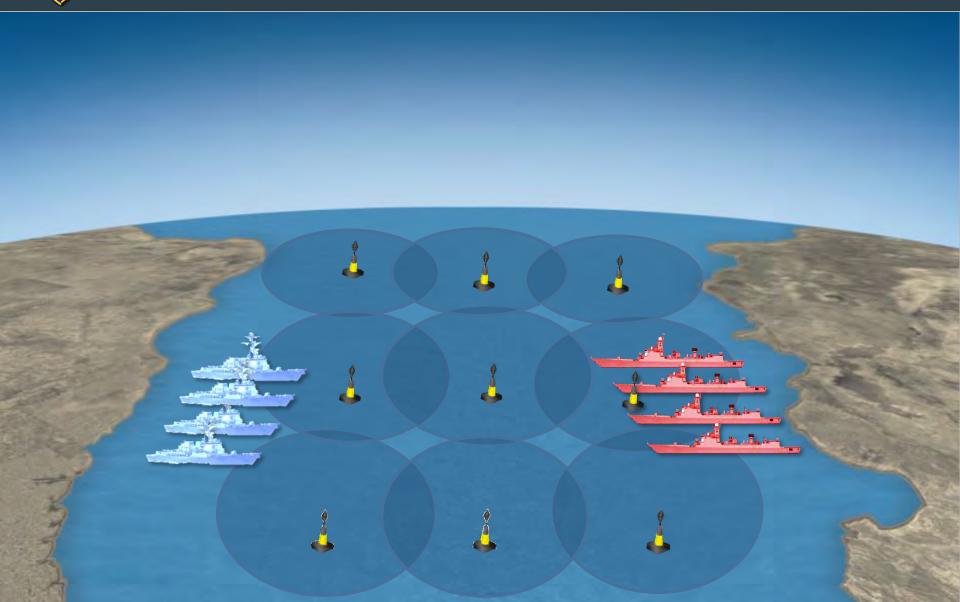
Expectations/Limitations

- 24/7 availability
- Demonstrated reliability over the domain area
- Access coverage sea dominance
- Maintenance

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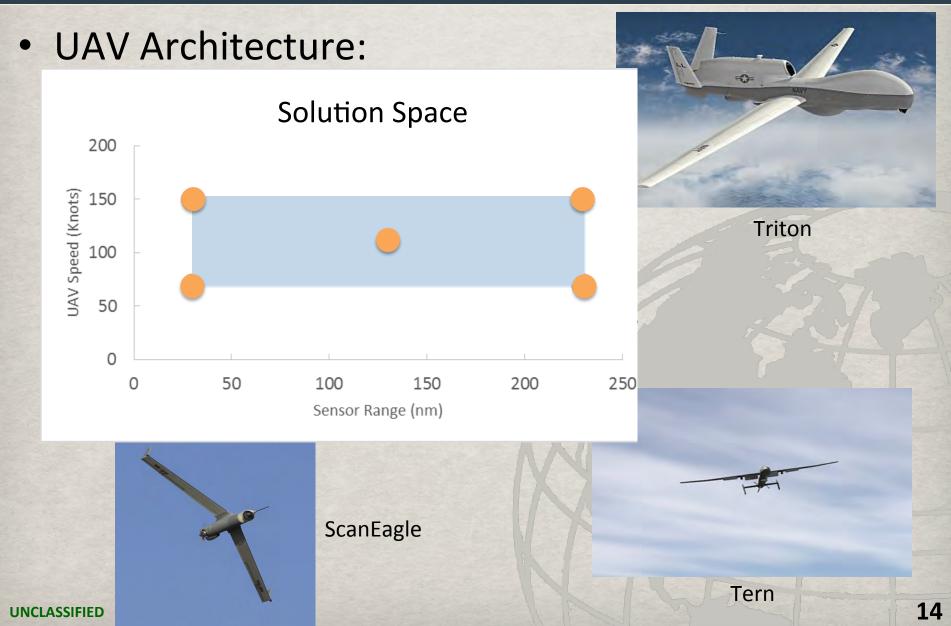
Prepositioned Network CONOPs



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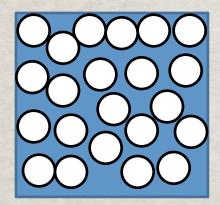
Representative System Configurations



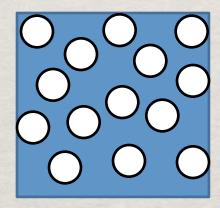


Representative System Configurations

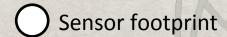
PPN Architecture:

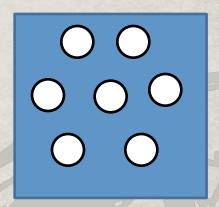


PPN 1 95% coverage 53 sensors



PPN 2 66% coverage 37 sensors

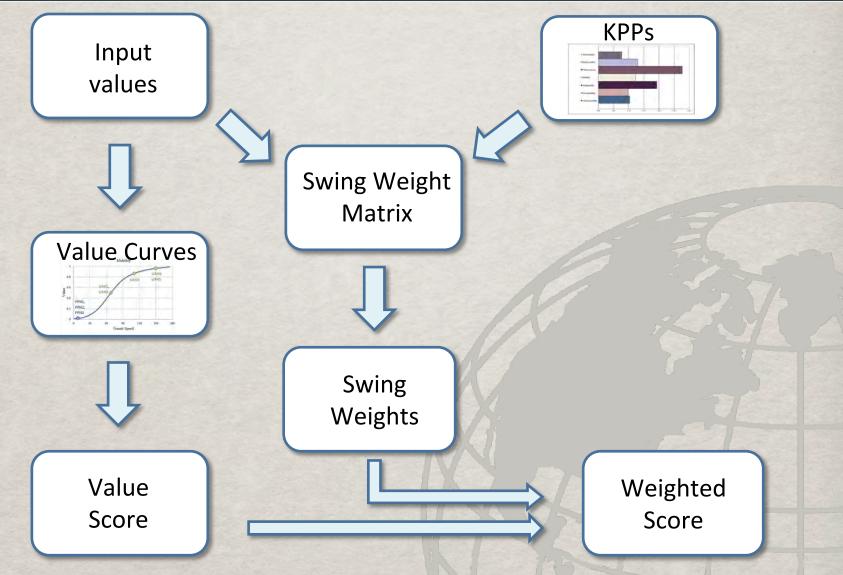




PPN 3
33% coverage
19 sensors

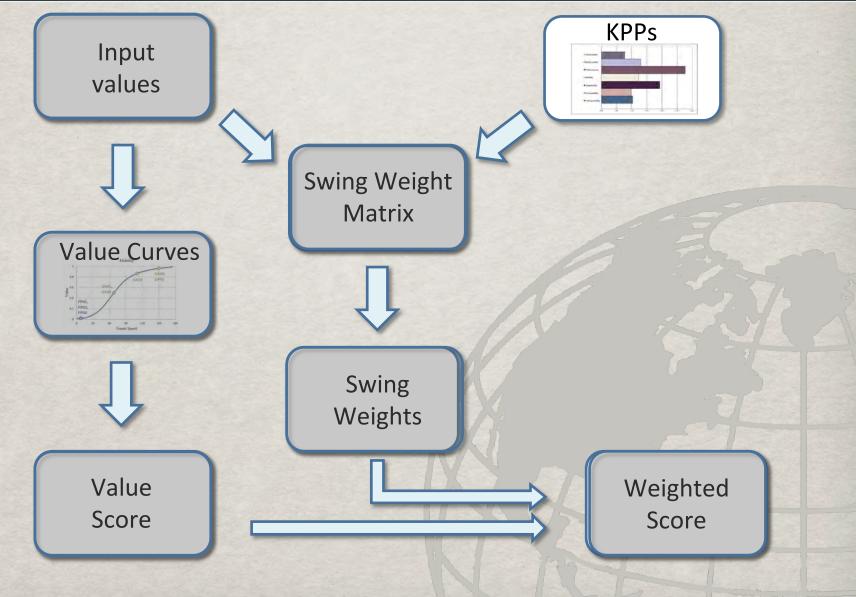


Effectiveness



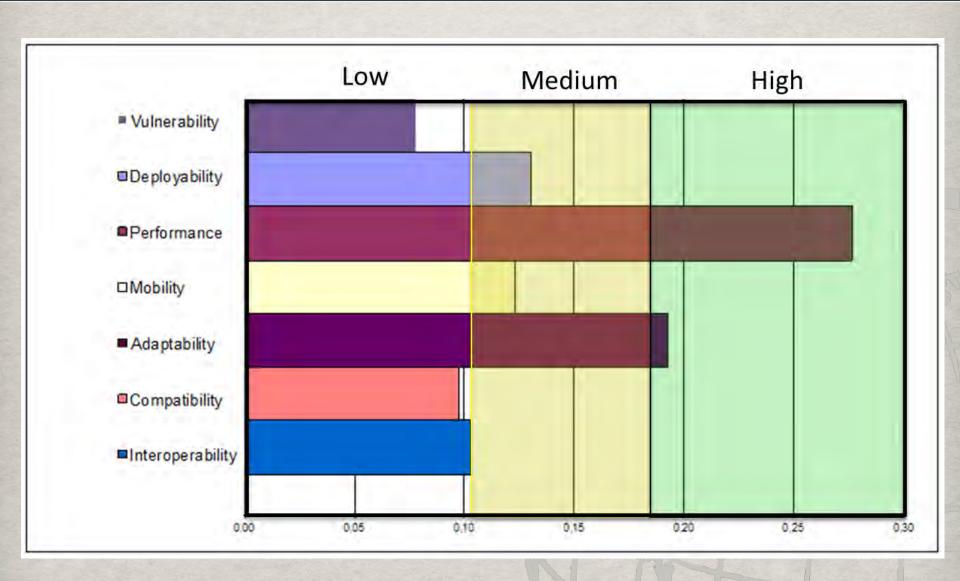


Effectiveness





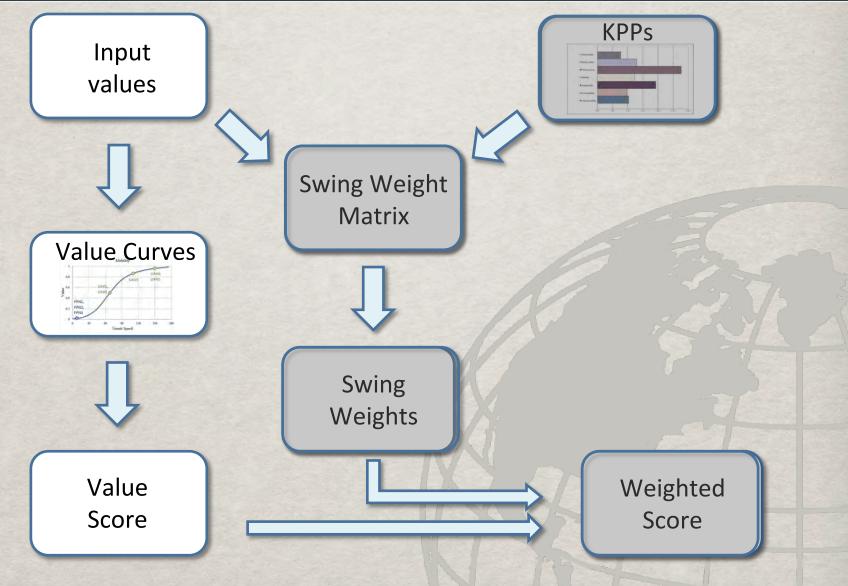
Identifying Significant KPPs



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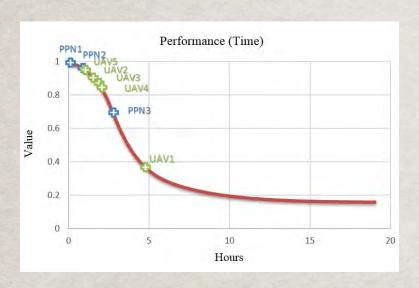


Effectiveness

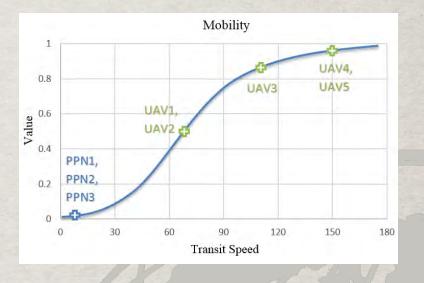


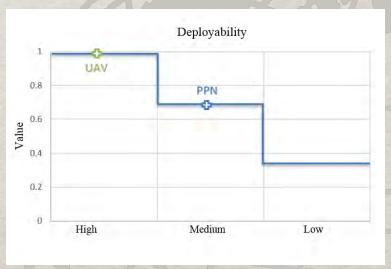


Defining Value Curves



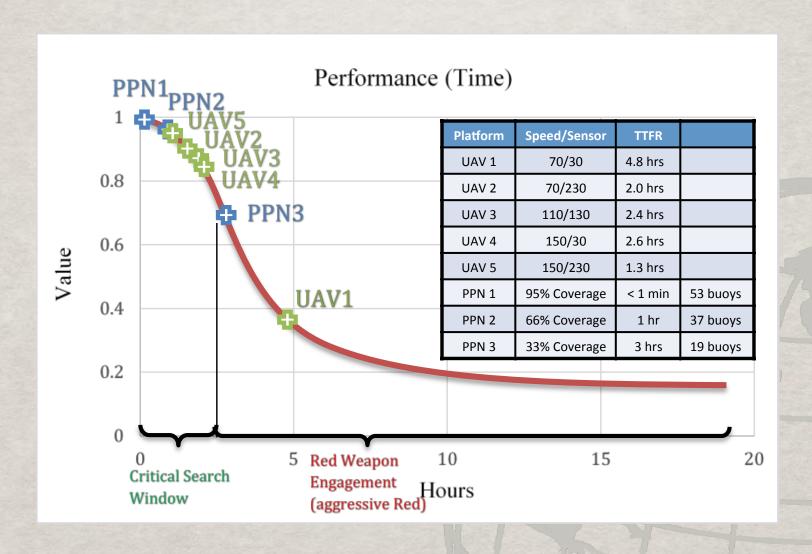








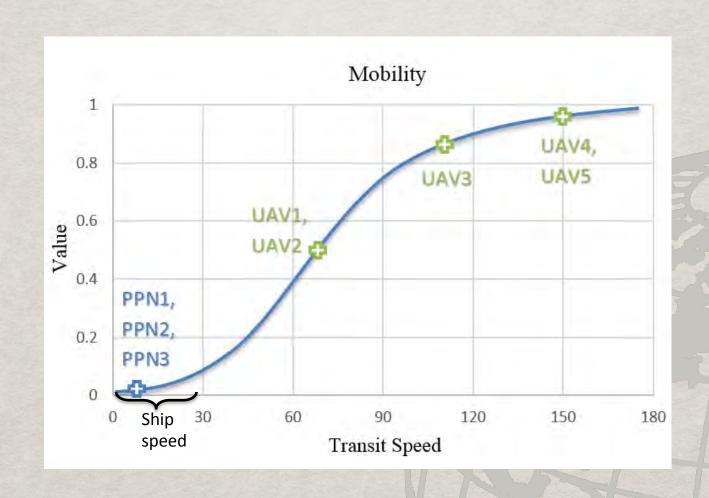
Value Curves: Performance



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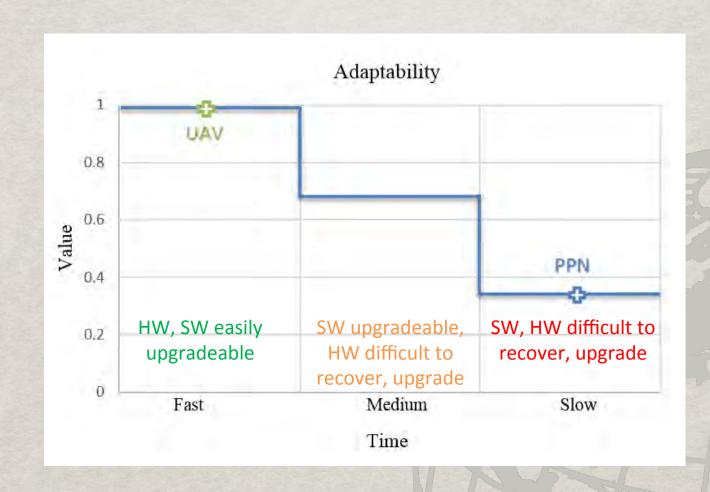


Value Curves: Mobility



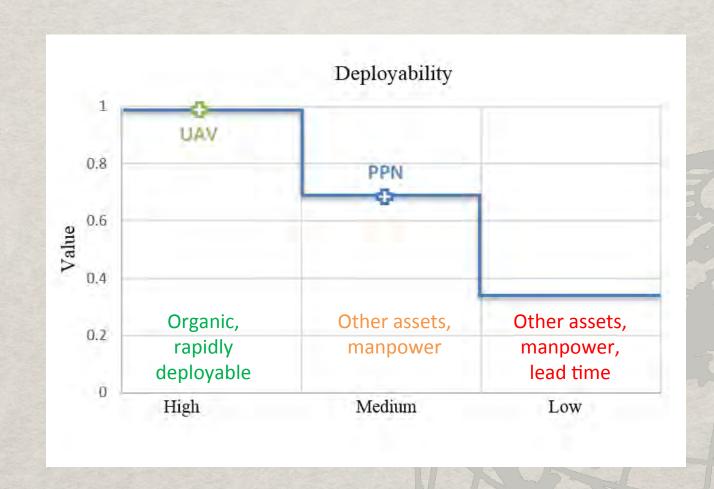


Value Curves: Adaptability



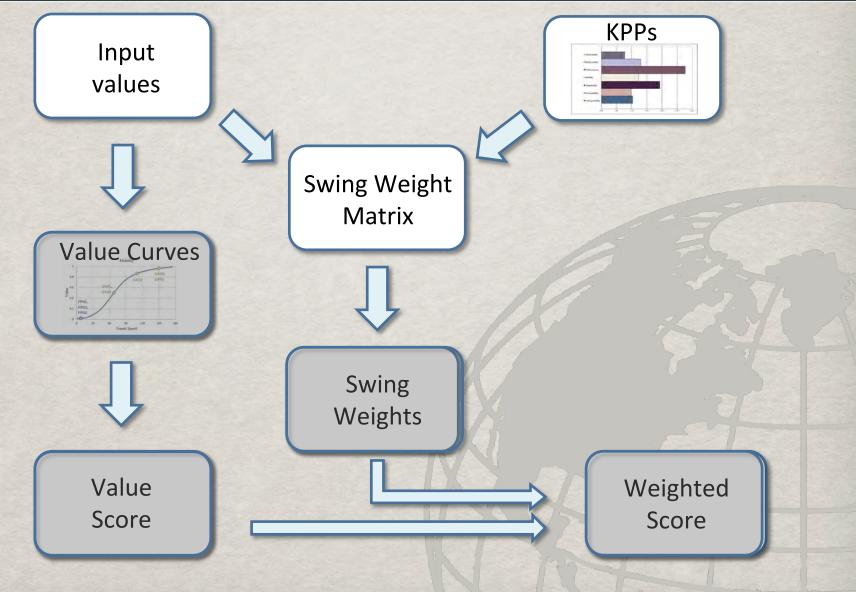


Value Curves: Deployability





Effectiveness



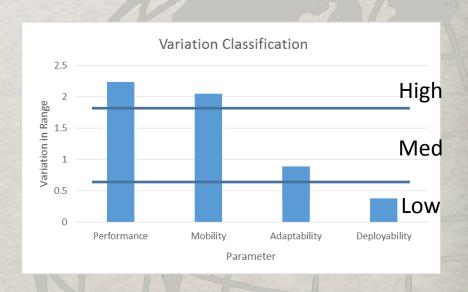


Swing Weights

Evaluation Measure	PPN1	PPN2	PPN3	UAV1	UAV2	UAV3	UAV4	UAV5	Var in Range	Var Class
Performance (hours)	0.02	1.0	3.0	4.8	2.0	2.4	2.6	1.3	2.23	High
Mobility (knots)	5	5	5	70	70	110	150	150	2.05	High
Adaptability (fast-med-slow)	33	33	33	99	99	99	99	99	0.89	Med
Deployability (high-med-low)	66	66	66	99	99	99	99	99	0.38	Low

Var in Range=Max-Min/Avg

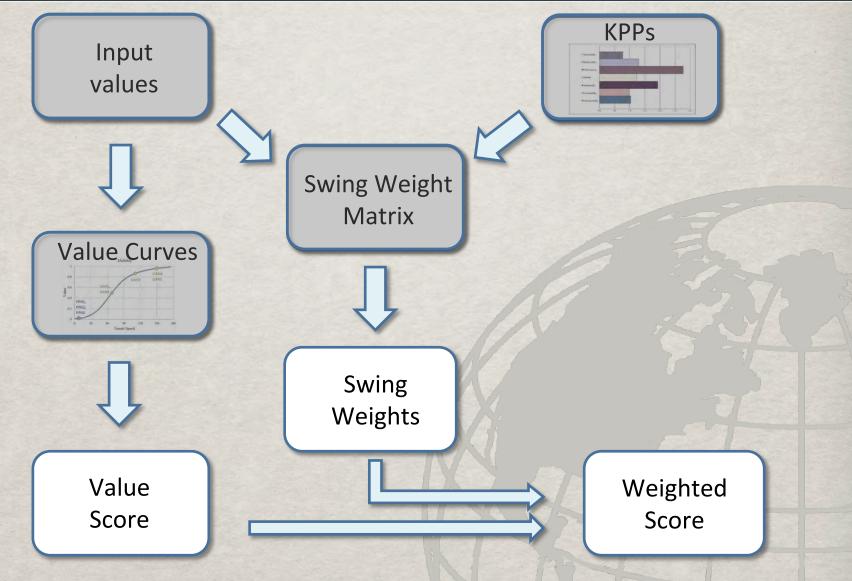
Variation	Importance						
in range	High	Medium	Low				
High	9 Performance Adaptability	6	3				
Medium	8	5 Mobility	2				
Low	7	4 Deployability	1				



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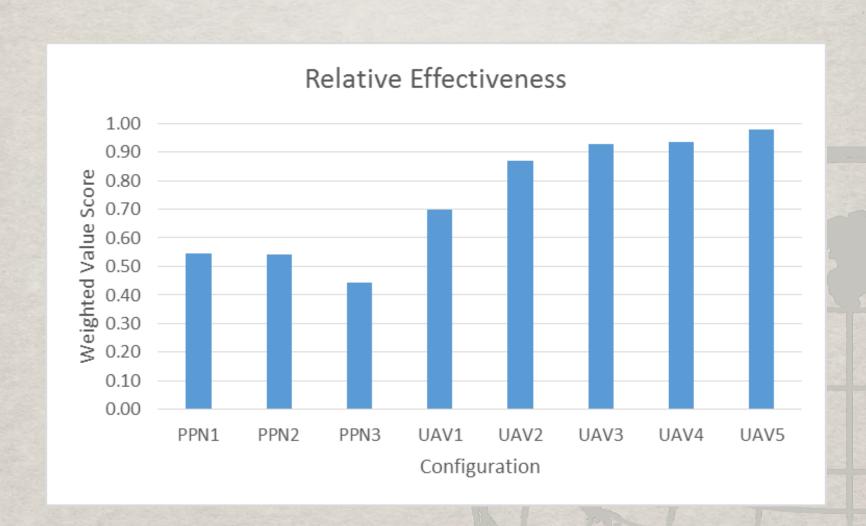


Effectiveness



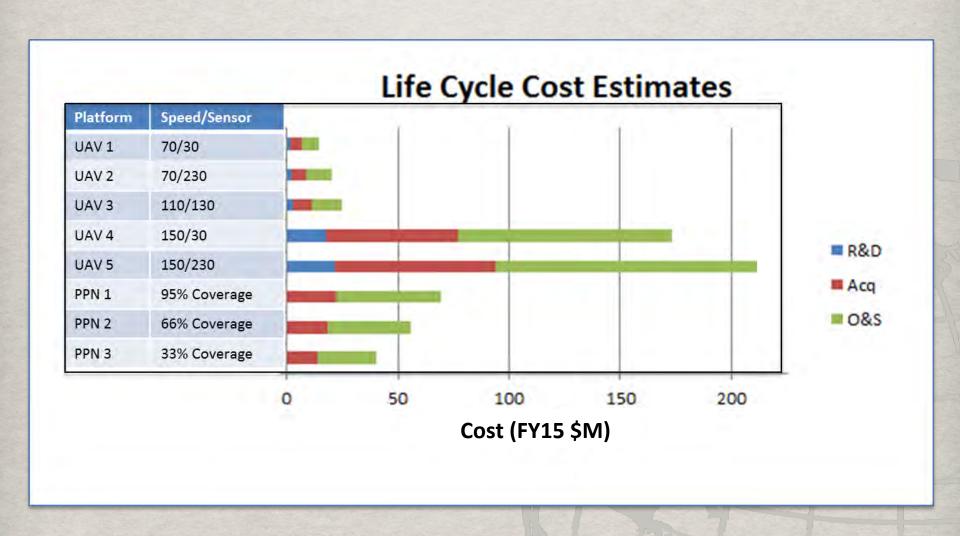


Weighted Scores





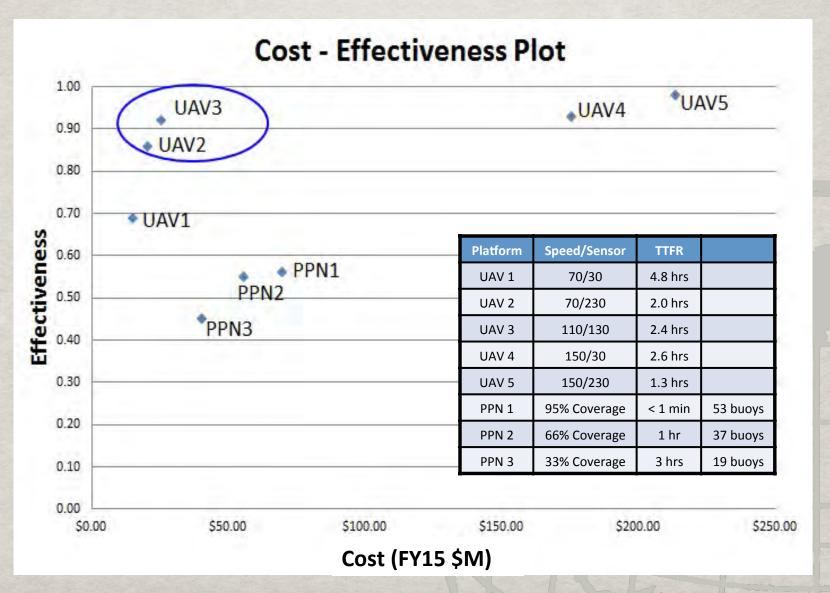
Cost Analysis



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Cost vs. Effectiveness



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Recommendations (1/2)

- Address ship-launched UAV integration challenges:
 - Hardware and software integration
 - Manpower and training
 - Launch, recovery, and logistics
- Pursue enabling technology for improving speed and range of ship-launched UAVs
 - Advanced materials
 - Energy storage
 - Component miniaturization



Recommendations (2/2)

- Encourage fleet engagement and experimentation to accelerate UAV adoption and employment
 - Early investment to elicit fleet input
- Engage with NWDC to develop CONOPS for organic employment of UAV systems
 - Integrate with ship-launched long-range ASCM



Areas for Further Study

- Explore additional modeling scenarios and architecture configurations
 - Hybrid PPN and UAV alternatives
- Assess impact of recommended solutions on Phase 0 operations
 - Persistent ISR coverage
- Anticipate adversary's technology advancement
 - Increased ASCM range



SEA-21A Capstone Project Team

