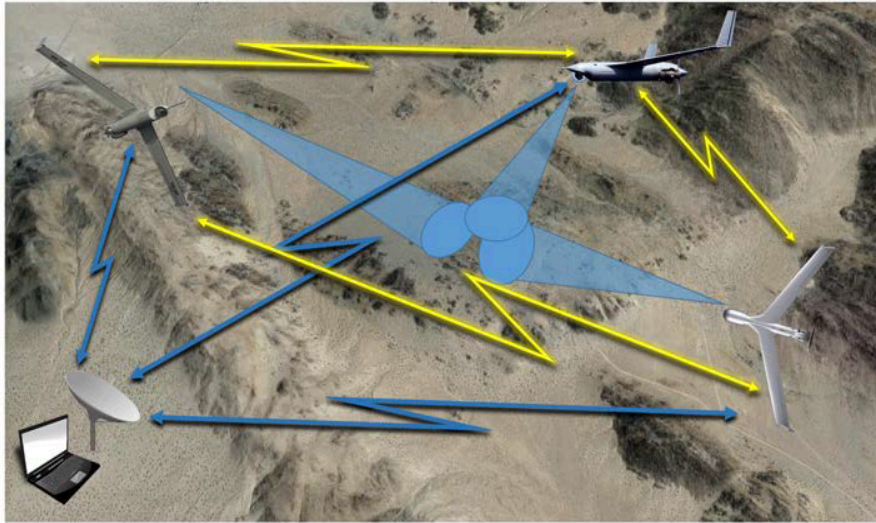
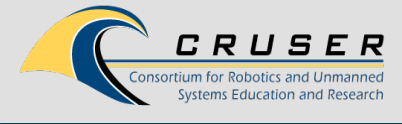


# Cooperative Autonomous ScanEagle



## How

- Further evolve the ScanEagle Command and Control Application Programming Interface
- Develop Camera Sensor Application Programming Interface
- Integrate Sensor and C2 Application Programming Interface
- Establish a set of predetermined optimal routes (Templates) that consider the Aircraft and Sensor dynamics.

## What

- UAS manpower limitations constrain the Navy's ISR capabilities
- Expand the Navy's capacity to FIND/FIX with less personnel
- Reduce the cognitive load on the operator
- Utilize autonomous path following to provide optimal routes for ISR missions
- Automate the locating of targets in the Information Operations (IO) and Intelligence, Surveillance and Reconnaissance (ISR) domains

## Objective

- Achieve autonomous behavior of a single ScanEagle UAV
- Advance combined cooperative and autonomous behavior of at least two ScanEagle UAV's
- Evolve the ScanEagle secondary controller
- Develop cooperative behavior using multiple ScanEagle UAV's
- Improvements to ISR payloads to enable their C2 of the Aircraft



**FY18 Call for Proposals**

Aurelio Monarrez  
amonarre@nps.edu

Dr. Sean Kragelund  
spkragel@nps.edu