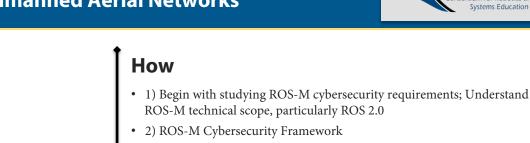
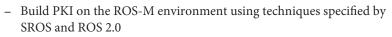
Study of Cybersecurity Requirements for the Military Robot Operating System (ROS-M) using ROS 2.0 on Unmanned Aerial Networks



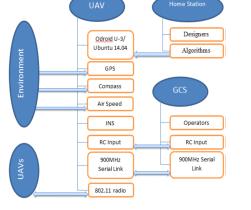


- Study management of public and private keys for PKI and how to securely disseminate keys among different ROS-M nodes
- Evaluate the ROS-M PKI via simulations of small UAV networks using the Gazebo simulation platform
- Evaluate how ROS-M cybersecurity mitigates different threat models

Why/Objective

- DoD is seeking to build a military centric ROS
- Implementation of ROS-M and ROS 2.0 is currently in its development phase
- Adoption of one operating framework (ROS-M) would lead to cost savings in program development cycles as well as an increase in reliability and operability
- Ability to securely control ROS-M enabled platforms free from adversarial interference is of the upmost importance.
- The proposed research is operationally relevant and will contribute to relevant thesis study for NPS students
- Cybersecurity is an important research and curricular component at NPS and thus furthers the mission of the school, Navy and DoD.

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(Adapted From Hartmann, <u>Steup</u> Figure 4 pg. 6)

• Representation of the UAV What/Deliverables

- Mahate Abirte Butity rist she Rth Un Par Gem tap It Bitie Viers Isting US autonomy can be achieved
- Assessment of the military socurity standards associated for open source osoftware and determine if such security practices can be implemented for ROS-M using Secure ROS (SROS)/ROS 2.0 as proposed by OSRF
- Study cybersecurity prin**Live En the XST Certvire** nment (public key infrastructure (PKI), key management for PKI and securing wireless channel through secure handshake) based on SROS and ROS 2.0
- Analysis of exploitation avenues for ROS-M on small aerial networks
- This is a continuation of work executed in FY17 in which security for the standard ROS 1.0 platform was investigated





CORSUSER Consortium for Robotics and Unmanned Systems Education and Research