

C2 Design for Asymmetric Advantage: Teams of Autonomous Systems & People



Naval
Postgraduate
School



Integrated Manned-Unmanned Missions

Approach & Method

- State-of-the-art computational experimentation
 - CTG mission task environment
 - 6 degrees of UAS autonomy x 4 levels of un/manned mission integration
 - Measure mission efficacy, delay, cost, risk, coordination load, others
- Model future CTG organization, C2 approach, mission assets & personnel
 - Assess performance with alternate, promising C2 designs
 - ID comparative strengths & weaknesses
 - Work backward to plan cost-effective, low-risk solutions
- Analytic results provide roadmap for Fleet implementation

Background & Motivation

- Issues with C2 for Teams of Autonomous Systems & People (TASP)
 - Tall org hierarchies, long decision chains, slow mission responses
 - Manned v unmanned org, skill, culture, cost & performance differences
 - Current C2 inadequate for next generation battlespace & A2AD
- Asymmetric advantage requires C2 redesign
 - Much more than *C2 technology*
 - Requires dynamic *C2 organization & redesign*
 - Organization, acculturation, education, training & sharing important too
- How to prepare for this future 5 – 10 years ahead?

Issues & Benefits

- Operationally important issues:
 - Numerous UAS will need to co-occupy same airspace-time (swarm)
 - Manned & unmanned aircraft will need to work together (TASP)
 - Aircraft from different ships, shores & nations will need to be integrated
 - Current C2 design likely to fail within 5 years
- Devising best solution is analytically intractable
 - Myriad alternate approaches, costs, benefits, risks & timeframes
 - Trial & error (OJT) with operational assets is expensive & error-prone
 - Computational experimentation is systematic, cost-effective, risk-free