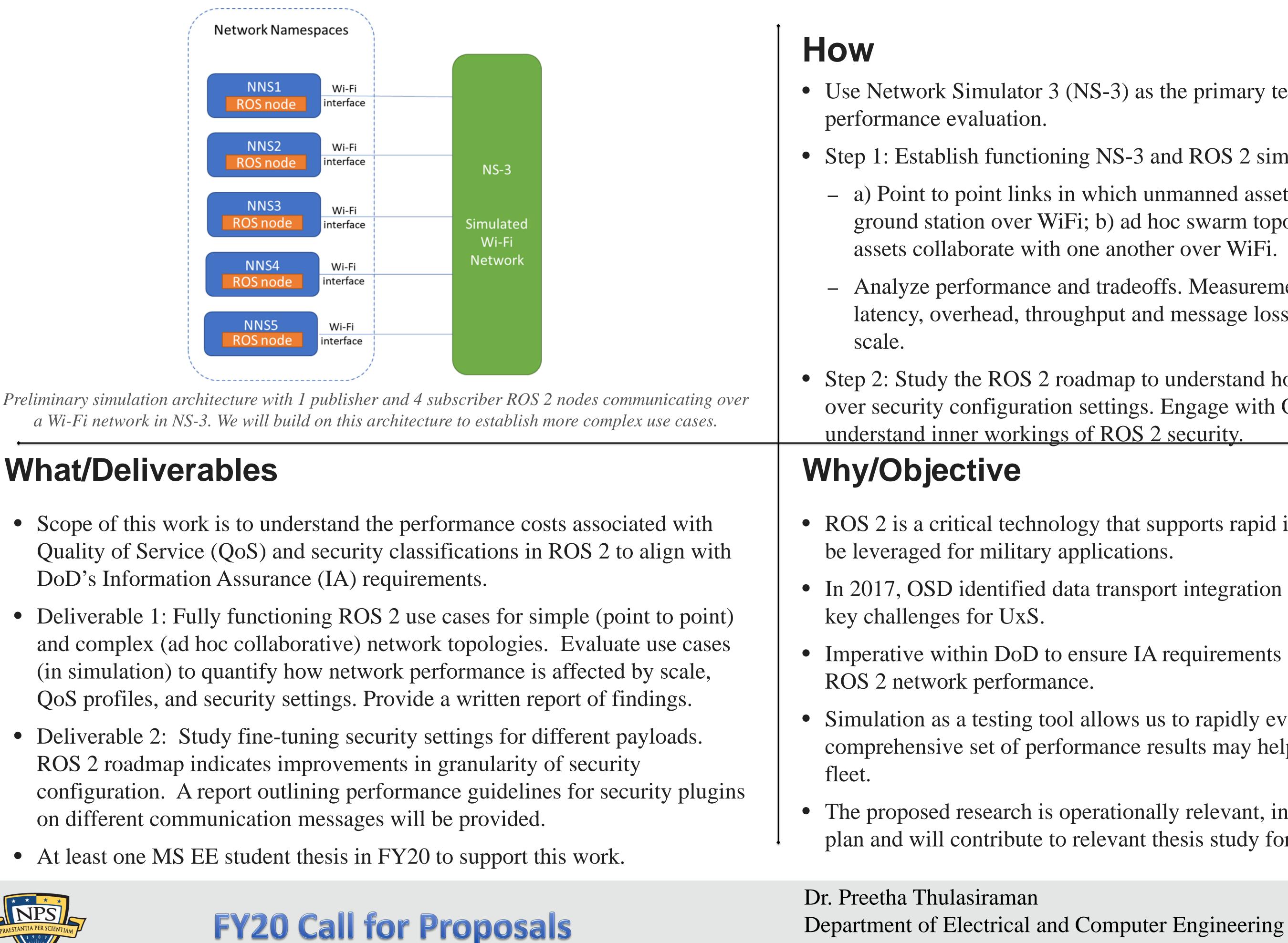
ROS 2 Cyber Network Performance Using Scalable Quality of Service and Security Classifications



What/Deliverables

- DoD's Information Assurance (IA) requirements.
- ROS 2 roadmap indicates improvements in granularity of security on different communication messages will be provided.
- At least one MS EE student thesis in FY20 to support this work.





• Use Network Simulator 3 (NS-3) as the primary testing tool for rapid

• Step 1: Establish functioning NS-3 and ROS 2 simulation setup to include

– a) Point to point links in which unmanned assets communicate with a ground station over WiFi; b) ad hoc swarm topology in which multiple

– Analyze performance and tradeoffs. Measurements will include: message latency, overhead, throughput and message loss as a function of network

Step 2: Study the ROS 2 roadmap to understand how to provide finer control over security configuration settings. Engage with Open Robotics to

• ROS 2 is a critical technology that supports rapid innovation of UxS and can

• In 2017, OSD identified data transport integration and cybersecurity as two

• Imperative within DoD to ensure IA requirements are met in the context of

Simulation as a testing tool allows us to rapidly evaluate performance. A comprehensive set of performance results may help ROS 2 transition to the

The proposed research is operationally relevant, in line with the NPS strategic plan and will contribute to relevant thesis study for NPS students

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